Monitoring Technique

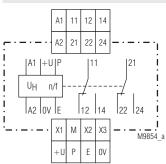
VARIMETER Speed Monitor MK 9055N, MH 9055



Product Description

The speed monitors MK 9055N and MH 9055 monitors the rotational speed of motors. They recognise and monitor impulse signals of e.g. proximity sensors and protect machines and produced material or allows speed depending switching in production processes.

Circuit Diagrams



Connection Terminal

Terminal designation	Signal description
A1+, A1	+ / L
A2	- / N
IN+, IN-, P, E	Measuring input
X1, X2, X3	Programming terminals
М	Ref. point programming terminals
UA	Analogue output voltage
IA	Analogue output current
+U / 0V	Sensor supply and alternative external auxiliary voltage DC 24 V
11, 12, 14; 21, 22, 24	Speed error-Indicator relay (2 changeover contacts)

Translation of the original instructions

Your Advantage

- · Protection of persons, machines and products
- Easy setting
- Universal input, for configuration of different sensors
- (PNP, NPN, 2-wire, contact, voltage) With fast reaction at low speed

Features

- According to IEC/EN 60255-1
- Detection of high or low-rpm / stand still (adjustable function)
- Large setting range 1 ... 120.000 IPM or
- 0.15 ... 20.000 Hz (10 ranges each)
 As option with input for NAMUR-sensors with sensor and wire protection against interruption and short circuit
- Adjustable hysteresis 0.5 ... 50 %
- Adjustable start up time delay 0 ... 50 s, control with external contact
- Adjustable monitoring time for missing input signal at function overfrequency; additional using as standstill level
- Programmable via termminals:
 Alarm delay of 0 ... 100 s
- With manual reset or auto resetLED-indication for auxiliary voltage, measuring input and output relay;
- additional LED for indication of wire- / sensor failure at NAMUR-input
- Auxiliary voltages AC 230 V and DC 24 V in one unit
- 2 changeover contacts, closed circuit operation
- Open circuit operation on request
- As option with analogue output, proportionally to speed
 Device available with 2 response values and seperately controlled output relays for under- and overfrequency see MK 9055N/5__
- MH 9055 with wide input range for auxiliary voltage (AC/DC 24 ... 60 V or AC/DC 110 ... 230 V)
- 2 possible compact designs MK 9055N: Width 22,5 mm
- MH 9055: Width 45 mm

Approvals and Markings

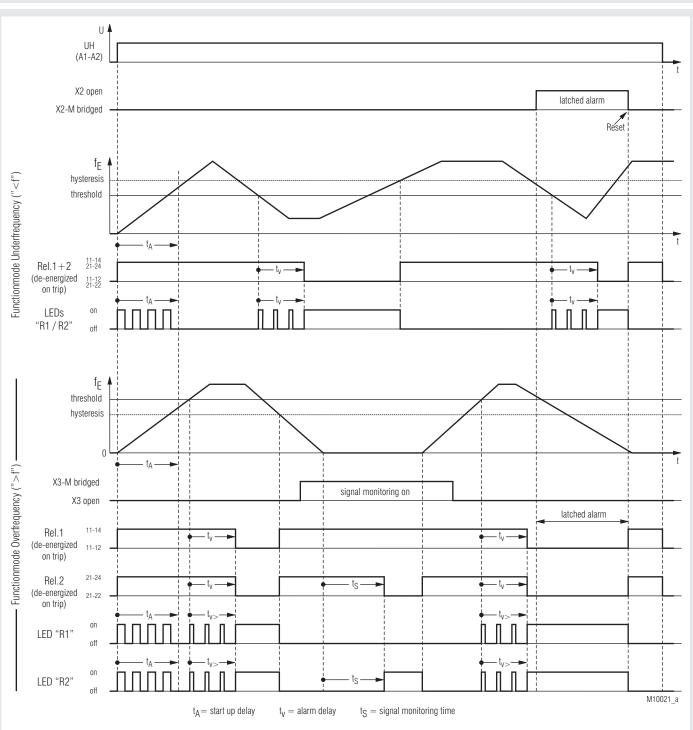


1

Applications

- Speed monitoring on rotating machine parts
- Monitoring of cyclic movements
- General monitoring of pulse sequences (transportation, conveyors, production systems),
- Monitoring of pulse frequency (e.g. flow sensors, anemometers)

Function Diagram



Function

The auxiliary supply is connected to terminals A1-A2. An operation with alternatively DC 24 V is possible via terminals +U / 0V.

Different sensors can be connected to the measuring input that detects the speed pulses.

The input frequency is compared to the setting value (response value = fine tunig x range).

As the device measures the periods duration the fastest frequency measurement is possible.

In overfrequency mode (switch on front in pos. ">f") the output relays switches to alarm state if the input frequency rises above the response value for a longer time then selected on the terminals. If the measuring frequency drops again under the hysteresis value, the output relay switches back to good state without delay.

In underfrequency mode (switch on front in pos. "<f") the output relays switches to alarm state, if the input frequency drops below the response value for a longer time then selected on the terminals. If the measuring frequency rises again above the hysteresis value, the output relay switches back to good state without delay.

If manual reset is chosen, the output relay stays in tripped position, even

if the frequency is back to normal. The reset is made by bridging terminals X2-M or by disconnecting the auxiliary supply. In alarm state the yellow LEDs "R1" / "R2" are continuously on, during time

delay they flash with short pulse.

In de-energized on trip mode the output relay is energized in good state (contacts 11-14, 21-24 etc. closed).

In energized on trip mode the output relay is energized in alarm state (contacts 11-14, 21-24 etc. closed).

If start up delay is selected a timer is started after connection of auxiliary

supply that disables the measuring circuit for the adjusted time on terminal X3.

During this time the frequency measurement is disabled, the yellow LEDs "R1" and "R2" flash symmetrically and the output relays remain in "good" position.

This start up delay avoids an alarm e.g. when starting a generator or motor. In overfrequency mode missing input signal can be monitored as option: If the signal is missing longer then the selected monitoring time, relay 2 (contacts 21-22-24) and LED "R2" indicate alarm.

The variant /010 (NAMUR sensor input) includes broken wire and short circuit monitoring of the sensor and connection wire. A red LED indicates this failure and the output relays switch off.

Indicators

Upper LED "UH/E":	- Green:	Auxiliary supply is present, measuring input is Low				
	- Yellow:	Auxiliary supply is present, measuring input is High				
		nt red/green flashing if U _H and uence present				
Red LED "Sen.Err":		•				
(only at NAMUR input)	,	On, when broken wire or interruption at sensor ciruit detected				
Lower LED "R1" (yellow)	, ,	alarm state (under- / overfrequency) th short pulse) when time delay is				
Lower LED "R2" (yellow)		On, when alarm state (under- / overfrequency) flashes (with short pulse) when time delay is active				
		ilashes at signal monitoring alarm and "R2" flash together during				

Setting	
LED red: Sensor failure (only at MK9055N/010) LED yellow:	At 1 7 7 14 At 1 7 7 14 At 1 7 7 14 At 2 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7
Selector switch: for mode over or underfrequency	$\left.\begin{array}{c} \overbrace{f} \\ \overbrace{f} \\ \overbrace{g} \\ \overbrace{g} \\ \overbrace{g} \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $
+ U/0V: alternative U _H DC 24V	$\begin{array}{c c} & & & & \\ \hline X & & & & \\ \hline X & & & & \\ \hline Y & \\ Y & & \\ \hline Y & & \\ Y & & \\ \hline Y & & \\ \hline Y & & \\ Y & \\ \hline Y & & \\ Y & \\ Y & \\ \hline Y & \\ Y &$

start up delay

Notes

Universal measuring input

The universal input of the speed monitor (terminals +U, P, E, 0V) can handle a large variety of sensors (inductive or capacitve proximity sensors, ultra sonic, halleffect, optical sensors, light barriers, reed contacts etc.). The input is suitable for all sensors according to IEC / EN 60947-5-2 (VDE 0660 part 208).

Depending on the sensor that is used (3-wire PNP or NPN, 2-wire, contact) the connection to the input terminals could be different (see Connection Examples).

As the speed monitor is suitable for a very high maximum frequency, RCelements need to be installed to suppress bouncing of contact sensors (see Connection Examples). It is possible to use standard RC-elements suitable for contact protection or RF interference protection.

NAMUR input

The Variant $M_{\rm 9055N}/010$ is optimzed for the connection of NAMUR sensors according to IEC / EN 60947-5-6 (VDE 0660 Teil 212; former EN 50227 / DIN 19234). These 2-wire-sensors are connected to terminals IN+ / IN-(see application example).

Namur sensors have a defined current in ON as well as in OFF state. This allows to detect short circuits and broken wire on sensor and connection wires with this variant. Together with the upper green/yellow LED the type of failure is indicated:

Red LED "Sen..Err" ON and upper LED "UH/E" lights up green:

Broken wire at input circuit

Red LED "Sen..Err" ON and upper LED "UH/E" lights up yellow: Short circuit at input circuit

Instead of a NAMUR sensor also a contact sensor with correspondent resistor circuit can be used (see Connection Examples). The suggested resistors are necessary to avoid broken wire or short circuit detection alarm. If the resistors are connected directly on the sensor side, the wiring still is monitored. Because of contact bouncing of mechanical contacts a capacitor has to be connected on the measuring input terminals.

Sensor supply, 24V DC auxiliary supply as alternative

The input circuit (+U, P, E, 0V) is galvanic separated to the auxiliary supply A1, A2 (eg. AC 230V). By connecting AC 230V auxiliary voltage on terminals A1-A2 the unit provides a voltage of approx. 24 V max 20mA to supply external sensors. If the auxiliary supply is DC 24V or sensors with higher power consumption are used, the DC 24V auxiliary supply is connected to terminals +U / 0V. The sensors are also supplied from this source. (In this case there is no galvanic separation between auxiliary supply and measuring input).

Monitoring indicator of sensor input

The upper 2-coloure LED shows the connected supply voltage and the electrical state of the measuring input:

Green: Input E ist on LOW level

Yellow: Input E ion HIGH level

Depending on the type of sensor (PNP, NPN, 2-wire, NO or NC contact) the actual state (active or inactive) is indicated.

Green / yellow: Input pulses from sensor present

Several speed monitors on one sensor

Parallel operation of several speed monitors on one sensor is possible the universal input e.g. to monitor several speed levels. The corresponding terminals are all connected in parallel.

Start up delay / monitoring of measuring signal.

The start up time delay (t_A) can be adjusted with the lowest potentiometer on the front side of the unit and is activated when connecting the auxiliary supply. If no start-up delay is required the potentiometer is turned fully antic-clockwise (t=0).

In underfrequency mode ("<f") the start up delay can be extended/restarted at any time with a control contact between terminals X3-M. As long as

X3-M is bridged the start up delay is continuously on and the frequency is not measured. When the link on X3-M is opened the start up delay time restarts.

In overfrequency mode (">f") with a bridge on X3-M, the lowest potentiometer sets the measuring signal monitoring time (t_s) (The adjusted time values t_a/t_s are identically).

Notes

When signal monitoring in mode ">f" is selected by bridging X3-M the measuring input is monitored as follows:

If during the adjusted monitoring time interval no measuring signal is detected, measuring signal alarm is indicated. As soon as the measuring signal returns the alarm status is reset (auto reset selected) and the monitoring interval t_s starts again.

The alarm status is indicated on relay 2 (contacts 21-22-24) and LED "R2" and can be easily differentiated from under/over frequency alarm where both relays (contacts 11-12-14 and 21-22-24) and LEDs "R1"and "R2") are active.

The detection of missing measuring signal can increase the safety in critical applications on overfrequency. It detects if the measuring signal is connected to the input of the device and works correctly: It can be checked if the frequency input still delivers pulses. If a Namur sensor is used with variant /010 higher safety can be achieved by the integrated short circuit and broken wire detection.

Second speed level / detection of overspeed and standstill

The signal monitoring time setting in the overfrequency mode can also be used as second speed level, e.g. to detect standstill in addition to overspeed. To achieve this, the monitoring time is adjusted on the lower potentiometer to the reverse value of the pulse frequency that indicates standstill.

Programming terminals (M-X1-X2-X3):

- Attention! The terminals M-X1-X2-X3 have no galvanic separation to the measuring circuit (+U / P / E / 0V) e.g. auxiliary voltage DC 24 V
- M: Common connection (Ground) of the programming terminals (identically with 0V)
- X1: A response delay of 0...100 s after connection of auxiliary supply is achieved by connecting a X1 to M with a potentiometer or fixed resistor (0.25 W) see technical data. The delay can be stopped by bridging X1 to M at any time. If no start up delay is required the terminals X1-M must be linked.
- X2: Manual reset with NO contact push button on X2-M, auto reset with terminals X2-M bridged.
- X3: When X3-M is bridged in mode "underfrequency" the start up delay is continuously active or the time is restarted. In mode overfrequency the monitoring of the measuring signal is switched on by bridging X3-M.

Adjustment aid for start up delay and alarm delay

During the elapse of start up delay and alarm delay the yellow LED "R1" and "R2" is flashing with a frequency of 2 Hz. To set a specific time value in seconds the number of flash pulses can be used to check the setting: Number of flash pulses divided by 2 = time delay in seconds.

Variants with Analogue Output Indicating the Actual Speed / Frequency

With this variant the programming terminal X3 is replaced by terminal UA or IA, that provides an analogue signal proportional to the speed with reference to terminal 0V. This signal is either 0 ... 10 V or 0 ... 20 mA or 4 ... 20 mA. As the X3 terminal is not available, these variants do not offer indication of missing speed signal in overfrequency mode and the start up delay can only be initiated when the auxiliary supply is switched on.

With the variant /017 (NAMUR sensor input with analogue output 4 \dots 20 mA) the analogue output also indicates a sensor or wiring failure by switching the output to 0 mA.

The analogue output has no galvanic separation to measuring input and the alternative auxiliary supply on terminals +U/0V

Technical Data

Frequency Measuring Input

Universal Input (+U / P / E 0V)

For PNP-, NPN-, 2-wire sensors, contacts and voltages, connection see application examples;

suitable for all proximity sensors according to IEC / EN 60947-5-2 (VDE 0660 part 208)

built in power supply approx. DC 24 V / max. 20 mA on terminals +U / 0V; Alternatively external auxiliary voltage supply DC 24 V via terminals +U / 0V

2 mA (OFF state)

8 V (ON state)

Approx. 17 kΩ

< 8 V

≥ 11 V

Max. residual current

At 2-wire sensors: **Max. voltage drops** At 2-wire sensors: **Voltage control** Input resistance: Low-capability: High-capability:

NAMUR Input (Variant /010) IN+ / IN-

For NAMUR sensors according to IEC/EN 60947-5-6 (VDE 0660 part 212 No-load voltage: Approx. 8.2 V					
Input resistance: Short circuit current:	Approx. 1 kΩ Approx. 8 mA				
response value					
Low:	Typ. 1.55 mA				
High:	Typ. 1.75 mA				
Broken wire threshold:	≤ 0,15 mA				
Short circuit threshold:	≥ 6 mA				

Alternatively external auxiliary voltage supply DC 24 V $\,$ via terminals +U $/\,$ 0V $\,$

Common Data for Inputs

response value

10 rang	ges:	1 120.000 IPM								
range	1	2	3	4	5	6	7	8	9	10
Imp. /	1	3	10	30	100	300	1.000	3.000	10.000	30.000
1 1	to	to	to	to	to	to	to	to	to	to
min	4	12	40	120	400	1.200	4.000	12.000	40.000	120.000

	or 0.15 20.000 Hz									
range	1	2	3	4	5	6	7	8	9	10
	0.15	0,5	1,5	5	15	50	150	500	1.500	5.000
Hz	to	to	to	to	to	to	to	to	to	to
	0.6	2	6	20	60	200	600	2.000	6.000	20.000

Infinite 1:4

1.5 kHz

5 kHz

25 kHz

350 µs

100 µs

20 µs

Infinetely variable: 0.5 ... 50 % of the setting response value

Duration of 1 cycle (inverse value of adjusted frequency) + 10 ms (at over frequency: inverse value of signal frequency + 10 ms)

(Alarm delay set to 0)

2 %

Fine adjustment: **Max. input frequency** (Impuls : Pause = 1 : 1) Range 1 ... 4: Range 5 ... 7: Range 8 ... 10: **Min. pulse- and breaktime** Range 1 ... 4: Range 5 ... 7: Range 8 ... 10: **Stability of the setting threshold at variation of auxiliary voltage and temperature: Hysteresis:**

Reaction time of Frequency monitoring:

Technical Data

Response delay:

Adjustable 0 ... 100 s with resitor/potentiometer across terminals X1-M:

R / kΩ:											
t _v / s:	0	0.3	0.7	1.3	2.3	5	9	15	25	50	100

Time between connection of auxiliary supply and ready to mesure: Start up time delay /

signal monitoring time:

Approx. 0.4 s (with start up delay is 0)

Continously variable on logarithmic scale; $t_a: 0 \dots 50 \text{ s}, t_s: 0, 1 \dots 50 \text{ s}$

AC 115, 230, 400 V + DC 24 V each

Auxiliary Voltage (A1-A2; e.g. +U / 0V)

Auxiliary voltage U_{H:}

(via terminals +U / 0V) (Terminals +U / 0V has no galvanic separation to measuring input) AC/DC 24 ... 60, 110 ... 230 V (only for MH-version possible) Voltage range AC: 0.8 ... 1.1 U_L DC: 0.85 ... 1.2 Ü_н AC/DC: 0.75 ... 1.2 U_H **Frequency range** 45 ... 440 Hz AC: Nominal consumption: Approx. 4 VA AC: DC: Approx. 2 W

Contact Output (11-12-14, 21-22-24)

Contacts: Thermal curren I _m : Switching capacity To AC 15	2 changeover contacts 4 A				
NO contacts:	3 A / AC 230 V	IEC/EN 60947-5-1			
NC contacts:	1 A / AC 230 V	IEC/EN 60947-5-1			
To DC 13					
NO contacts:	1 A / DC 24 V	IEC/EN 60947-5-1			
NC contacts:	1 A / DC 24 V	IEC/EN 60947-5-1			
Electrcal life					
To AC 15 at 1 A, AC 230 V:	1,5 x 10 ⁵ switch.cycl.	IEC/EN 60947-5-1			
Short circuit strength					
Max. fuse rating: Mechanicl life:	4 A gG / gL \geq 30 x 10 ⁶ switching c	IEC/EN 60947-5-1 ycles			

Analogue Voltage Output (variant /0_5, terminal "UA" against "0V")

Nominal output voltage:	0 10 V, linear proportional to the speed / frequency, without galvanic separation to measuring input and DC 24 V-supply Max 10 mA
Load: Scale:	Max. 10 mA 0 V at 0 IPM / Hz
ooulo.	5 V at setting end of scale value of speed / frequency 10 V at input frequency = 2 x end of
	scale value
Accuracy:	3 %
Analogue Output (variant /0_	_6, e.g. 0_7; terminal "IA" against "0V")
Output:	0 20 mA bzw. 4 20 mA, linear proportional to the speed / frequency, without galvanic separation to measuring input and DC 24 V-supply
Max. burden:	500 Ω
Scale:	0 mA e.g. 4 mA at 0 IPM / Hz
	10 mA e.g. 12 mA at setting end of scale value
	20 mA at input frequency = 2 x end of scale value
Fault signal at	Scale value
NAMUR input:	At output 4 20 mA (variant /017)
A	on sensor failure currentt drops tp 0
Accuracy:	3 %

Technical Data			Standard Type	
General Data			MK 9055N.12 1 120.000	IPM U _H AC 230 V
			Article number:	0058715
Nominal operating mode:	Continuous operatio	n	 Universal input for PNP-, N 	IPN-, 2-wire-sensors, contacts, voltage
Temperature range			 Selectable function: 	Over- or underfrequency
Operation:	- 20 + 60 °C		 Selectable signal monitorir 	o i j
Storage:	- 20 + 60 °C		• 10-fold selectable ranges:	1 120.000 IPM
Altitude:	≤ 2000 m		Response value unfinitely	
Clearance and creepage dis	stance		Hysteresis:	Adjustable from 0.550 %
Rated impulse voltage /			 Start up time delay / 	
pollution degree:			signal monitoring time:	Adjustable from 0 50 s
Contact to measuring input:	4 kV / 2	IEC 60664-1	Response delay:	Settalbe with external resitor to 0100 s
Contact to auxiliary circuit:	4 kV / 2	IEC 60664-1	 Alarm storing or auto-reserved 	
Contact to Contact:	4 kV / 2	IEC 60664-1	• Auxiliary voltage U _H :	AC 230 V + DC 24 V
Auxiliary circuit A1-A2 to			Closed circuit operation	
measuring input:	4 kV / 2	IEC 60664-1	Output:	2 changeover contacts
Programming terminals			Width:	22.5 mm
M-X1-X2-X3:	Without galv. separa	t. to measuring input		
Auxiliary voltage DC 24 V	Male and a l		MK 9055N.12 0,15 20.00	
(an +U / 0V):	Without galv. separa	t. to measuring input	Article number:	0058716
Analogue output, optional				IPN-, 2-wire-sensors, contacts, voltage
(UA / IA):	without gaiv. separa	t. to measuring input	Selectable function:	over- or underfrequency
EMC	$0 \left i \right\rangle \left(i \right)$		 Selectable signal monitorir 	
Electrostatic discharge: HF-irradiation	8 kV (air)	IEC/EN 61000-4-2	 10-fold selectable ranges: 	0,15 20.000 Hz
80 MHz 1 GHz:	12 V / m	IEC/EN 61000-4-3	Response value unfinitely	
1 GHz 2.7 GHz:	10 V / m	IEC/EN 61000-4-3	Hysteresis:Start up time delay /	Adjustable from 0.550 %
Fast transients:	2 kV	IEC/EN 61000-4-4	 Start up time delay / signal monitoring time: 	Adjustable from 0 50 s
Surge voltage	2		 Response delay: 	Settalbe with external resitor to 0100 s
Between			 Alarm storing or auto-rese 	
wires for power supply:	1 kV	IEC/EN 61000-4-5	 Auxiliary voltage U_H: 	AC 230 V + DC 24 V
HF-wire guided	10 V	IEC/EN 61000-4-6	 Closed circuit operation 	A0 230 V + D0 24 V
Interference suppression:	Limit value class B	EN 55011	 Output: 	2 changeover contacts
Degree of protection:			• Width:	22.5 mm
Housing:	IP 40	IEC/EN 60529	- main	
Terminals:	IP 20	IEC/EN 60529		
Housing:	Thermoplastic with \		Variants	
-	acc. to UL subject 94	1	Valianto	
Vibration resistance:	Amplitude 0.35 mm		M_ 905512/0	
	frequency 10 55 H	z IEC/EN 60068-2-6		
Climate resistance:	20 / 060 / 04	IEC/EN 60068-1	0 Standa	
Terminal designation:	EN 50005			ue output 0 10 V (instead of terminal X3)
Wire connection:	1 x 4 mm ² solid or			ue output 0 20 mA (instead of terminal X3)
	2 x 2.5 mm ² solid or		7 Analog	ue output 4 20 mA (instead of terminal X3)
	1 x 2.5 mm ² strande	d wire with sleeve		
	DIN 46228-1/-2/-3/-4	oder		sal input (standard)
	2 x 1.5 mm ² strande	d wire with sleeve	1 NAMU	R input with sensor monitoring
	DIN 46228-1/-2/-3/			
Wire fixing:	Plus-minus terminal	'	Ordering example for varia	nts
	terminals with wire p	rotection		
Fixing torque:	0.8 Nm		<u>MK 9055N</u> <u>.12</u> <u>/010</u> <u>1</u>	<u>120.000 IPM</u> <u>U_H AC 230 V</u>
Mounting:	DIN-rail	IEC/EN 60715		
Weight:	Approx. 210 g			Auxiliary voltage
				Response value
Dimensions				1 120.000 IPM or
				0.15 20.000 Hz
Width x height x depth:	00 5 00 05			Variant, if required Contacts
MK 9055N:	22.5 x 90 x 97 mm			

Dimensions

Width x height x depth: MK 9055N: MH 9055:

22.5 x 90 x 97 mm 45 x 90 x 97 mm

Accessory

NA 5001, NA 5002, NA 5005, NA 5010:

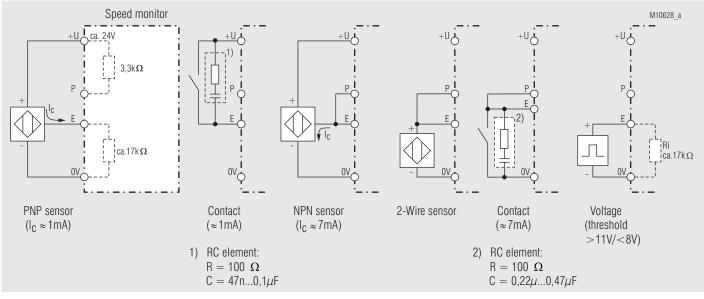
Proximity Sensors, induktive

Туре

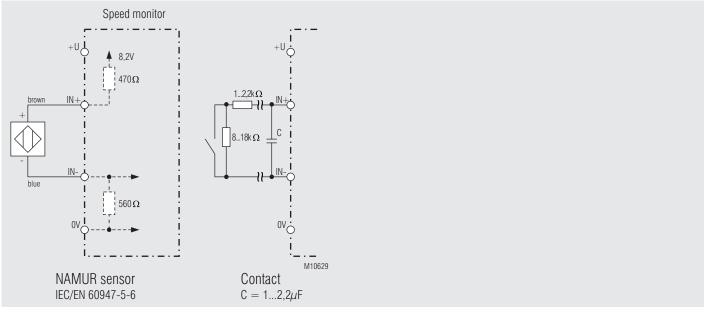


For further information on the proximity sensors, please refer to the associated NA 5001 data sheet at www.dold.com.

Application Examples



Universal input



NAMUR input only at M_ 9055.12/01_

E. Dold & Söhne GmbH & Co. KG • D-78120 Furtwangen • Bregstraße 18 • Phone +49 7723 654-0 • Fax +49 7723 654356