

ORIENTAL MOTOR U.S.A. Corp. 570 Alaska Avenue Torrance, CA 90503 1-800-GO-VEXTA (468-3982)

Item # EH4-AZAKH, Electric Gripper



The EH Series is a electric gripper based on a rack-and-pinion mechanism equipped with an AZ Series motor. Its delicate grip, like that of a human hand, assists in automation and labor-saving.

- Requires AZ Series DC Input Driver
- Connection Cables sold separately

Web Price

\$835.00

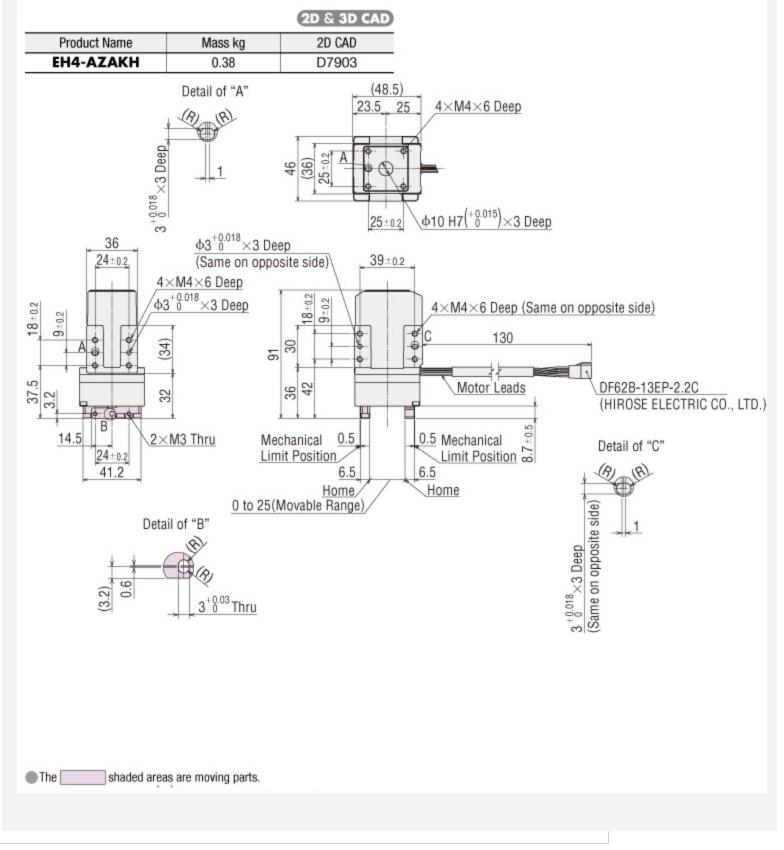
Specifications | Dimensions | Performance | System

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Lead Time ¹	Contact your local sales office for product lead-times, available to ship dates and shipping methods.
Actuator Frame Size	46 mm
Input Power	DC
Maximum Grip Force	25 N
Repetitive Positioning Accuracy (mm)	±0.02
Backlash	0.1 mm (each side)
Stroke	25 mm (12.5 mm each side)
Maximum Speed	156 mm/s (78 mm/s each side)
Maximum Acceleration	20 m/s ² (10 m/s ² each side)
Push Speed	20 mm/s (10 mm/s each side)

Minimum Travel Amount	0.02 mm (0.01 mm each side)
Permissible Load	5 N
Static Permissible Moment Load	M _P : 1.2 N·m M _Y : 0.12 N·m M _R : 0.4 N·m
Insulation Class	Class B [130°C (266°F)
Insulation Resistance	100 M Ω or more when 500 VDC megger is applied between the following places: Case - Motor and sensor windings
Dielectric Strength	Sufficient to withstand the following for 1 minute: Case - Motor and sensor windings 0.5 kVAC 50 Hz or 60 Hz
Ambient Temperature	0 ~ 40°C (32 ~ 104°F) (non-freezing)
Ambient Humidity	85% or less (Non-condensing)
Operating Atmosphere	Use in an area without corrosive gases and dust. The product should not be exposed to water, oil or other liquids.

Dimensions

Dimensions (Unit: mm)



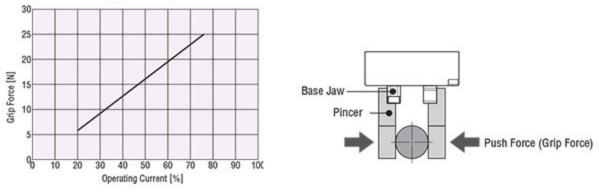
Performance

Relationship between Push Force (Grip Force) and Current

The gripping movement of the electric gripper depends on the push-motion operation. The push force (grip force) is s current of the motor.

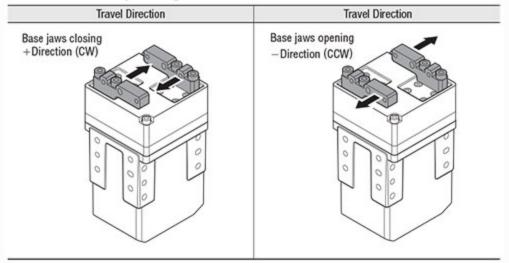
Actual Push Force (Grip Force)

The push force (grip force) and current values are shown below as a reference. Check it on the actual assembled equi



Travel Direction

The default factory setting for direction of travel is as follows:



System

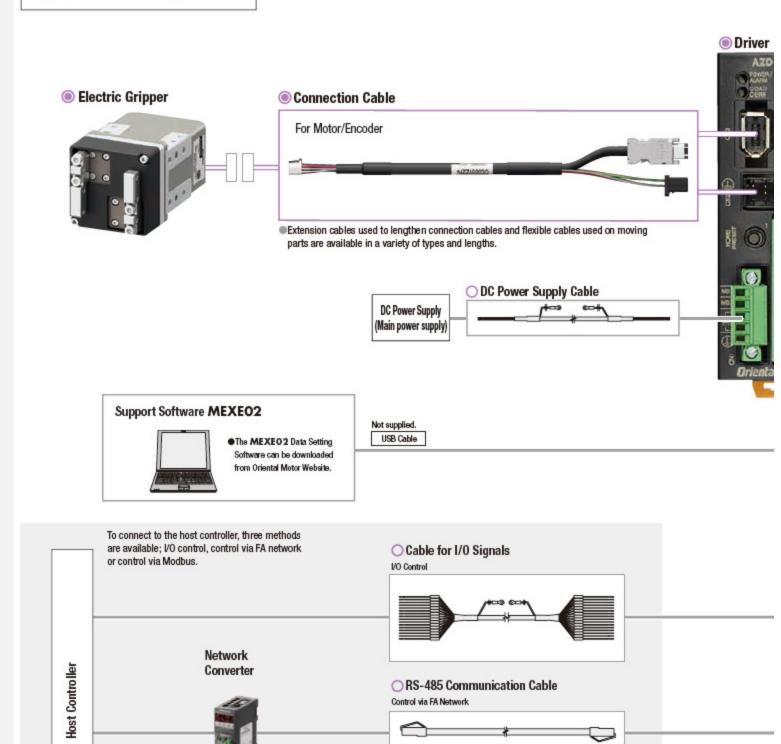
System Configuration

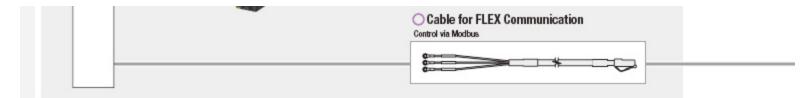
Combination of Electric Gripper and Built-in Controller Type Driver, or Pulse Input Type Driver with

An example of a configuration using I/O control or RS-485 communication is shown below.

Electric gripper, driver, and a connection cable/flexible connection cable are ordered separately. • For a pulse input type driver system configuration, please see the Oriental Motor website.

Required for operation Optional accessory

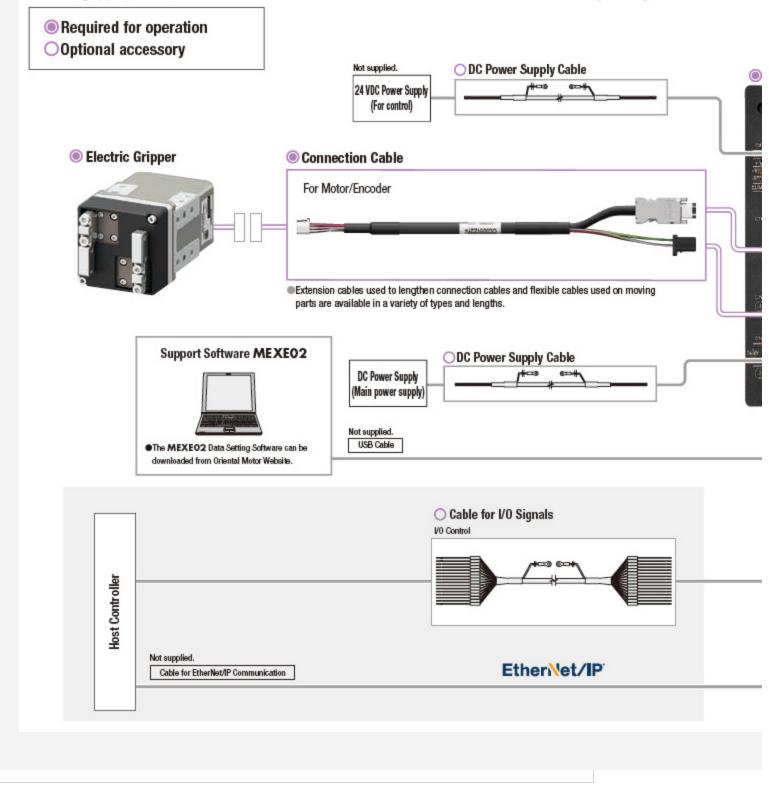




System Configuration

Combination of Electric Gripper and Network Compatible Driver

An example of a configuration using I/O control with an EtherNet/IP-compatible driver or EtherNet/IP is shown b Electric gripper, driver, and a connection cable/flexible connection cable are ordered separately.



¹ Quoted Ship Date for orders placed before 12:00 pm PST. Quantities may affect Shipping Date.

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